

## Multimodal Dialogue System for Intuitive Human Robot Interaction

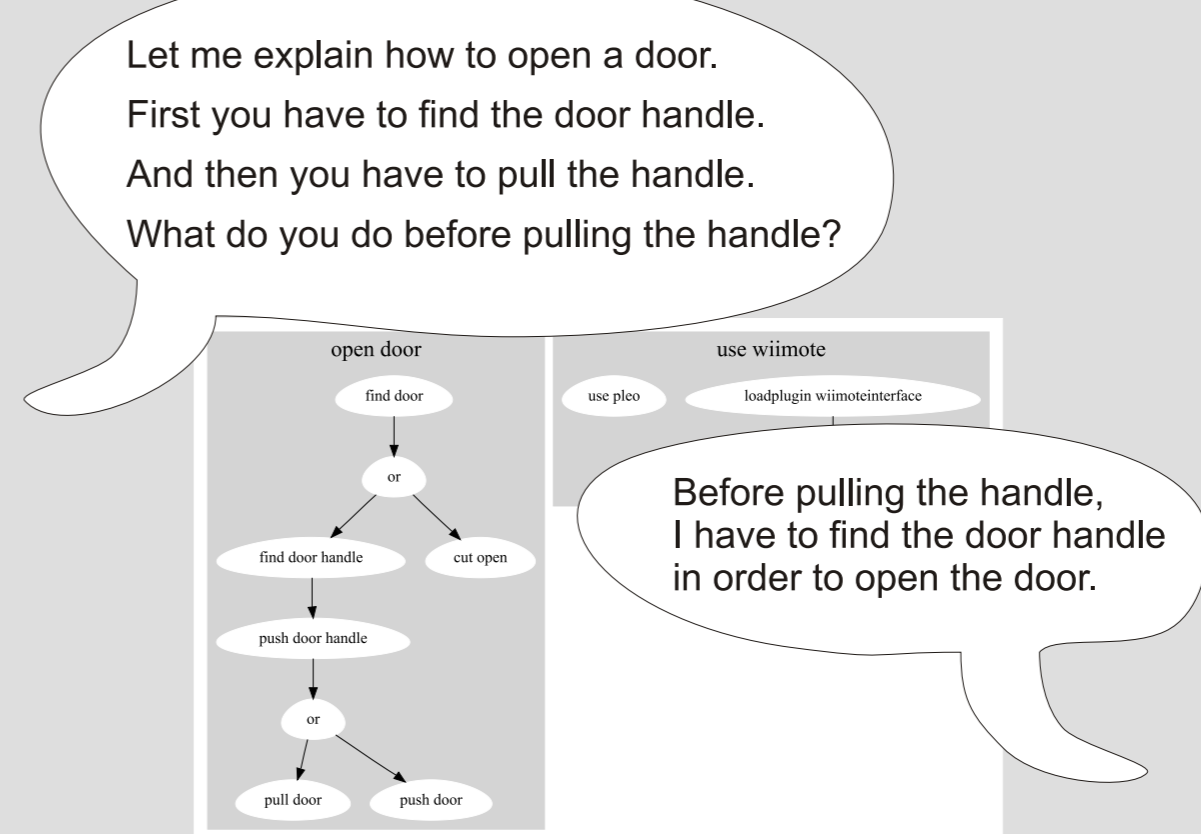
G. Rigoll, F.Wallhof, A.Knoll, B.Radig, B.Färber

### Towards a Multimodal Cognitive Dialogue

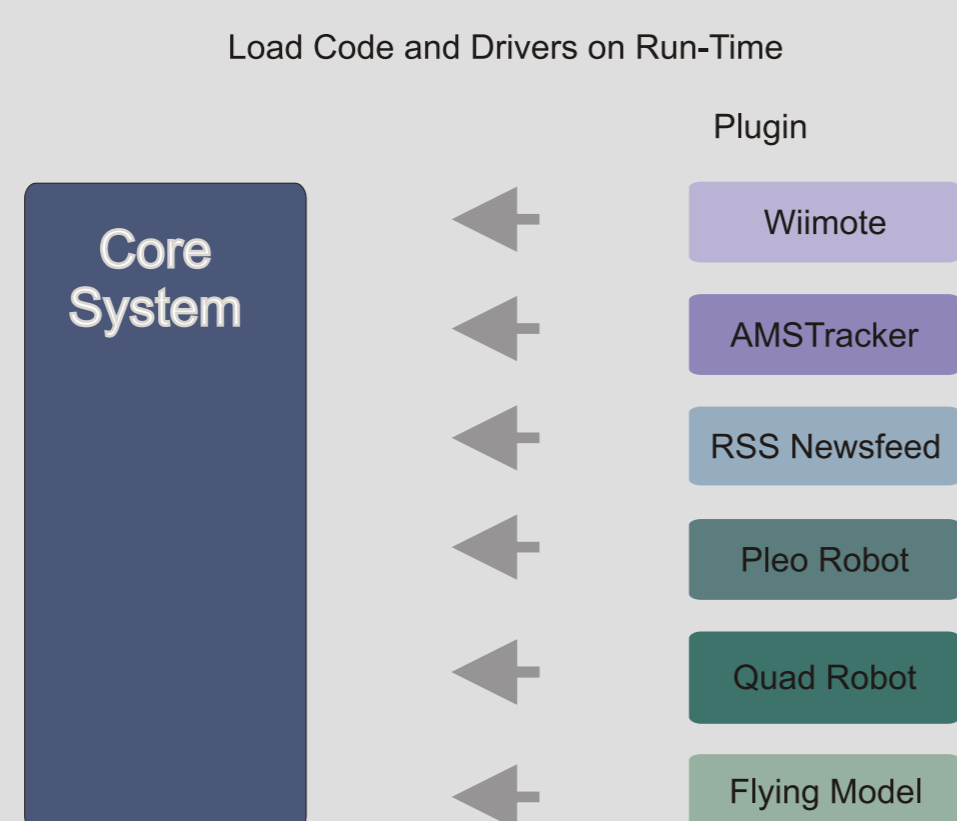
- Learns
- Understands
- Answers questions to proof understanding
- Visualizes system belief
- Rudimentary transfer of gained knowledge
- Connects to external gesture recognizers e.g. Wiimote

### Dialogue

Explain simple procedures, conditions and objects.  
Answers simple questions concerning structure and conditions.



### Interface External Systems with a Plugin-Technique



### Basic Features

Query Knowledge Base - for easier use, persistence and faster adaption:

- Load descriptions and scripts on run-time from database.
- Parses simple command scripts.

Use text and speech to control system and other networked components:

- Uses natural language (or gestures,...) to interact.
- Dialogue component: extensible grammar and vocabulary.
- Speech recognition: full dictation grammar and vocabulary.
- Optional use of command language for faster and direct access.

### Application Example

Pass Speech and Gesture Commands to a Ugobe Pleo



### Application

Control other objects:

